

Scope Statement Mechanical Arm



Need:

Mechanical device for the harvesting of space trash.

Scope Statement:

- The device must be able to grab pieces of trash no matter what they're made of.
- The device must be able to grab pieces of trash for which the longest side is at least 5 cm and at most 1m long.
- The tools and materials used to build the device must be chosen from the lists below.
- It must be possible for the device to be operated by a single user, without assistance.
- The device must come with a guide showing the user how to operate it.
- The device must allow the user to grab a piece of trash that is at least 1 m away.

Available Materials:

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- Wooden sticks
- String
- Cardboard
- Plastic bags

- Plastic containers
- Trombones
- Brass fasteners
- K-Nex gears

Tools

- Scissors
- Glue
- Adhesive tape
- Saw

- C-clamps
- Nails
- Hammer
- Pencils and crayons

evice Diagram:			
ser Guide:			



Scope Statement Magnetic Arm



Need:

Magnetic device for the harvesting of space trash.

Scope Statement

- The device must grab pieces of trash by using the force of magnetic attraction.
- The device must not contain any permanent magnet. Given the great quantity of trash in orbit, a permanent magnet would end up covered in trash in a matter of minutes! The device must therefore include an electromagnet and a switch.
- The tools and materials used to build the device must be chosen from the lists below.
- It must be possible for the device to be operated by a single user, without assistance.
- The device must come with a guide showing the user how to operate it.
- The device must allow the user to grab a piece of trash that is at least 1 m away.

Available Materials:

ELECTRIC SHOCK HAZARD: Do not use more than 4 batteries per device!

- Sheated copper wire
- 1,5 Volts battery
- Iron or steel screws
- Trombones

- Brass fasteners
- Cardboard
- Cardboard Tubes

Tools

- Scissors
- Glue
- Adhesive tape
- Saw

- C-clamps
- Nails
- Hammer
- Pencils and crayons

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ser Guide:			